



## AMENDMENTS TO THE CLAIMS

This listing of claims will replace all prior versions, and listings, of claims in the application:

### Listing of Claims

1       **Claim 1 (currently amended):** A location information  
2       transmission method for reporting on-road location  
3       information on a first digital map by an information  
4       transmission system, comprising the steps of:  
5              transmitting on-road location information by an  
6       information provider, the on-road location information  
7       including: a string of coordinates line information  
8       representing a road shape of a road section ~~having a~~  
9       ~~length determined depending on difficulty of shape~~  
10      matching; additional information including an information  
11     item selected from a group consisting of attribute  
12     information on said road section including a road  
13     location of said road section and detailed information on  
14     nodes in said road section;  
15              receiving said on-road location information by a  
16     receiver having a second digital map portable navigation  
17     apparatus; and  
18              performing shape matching to identify said road  
19     section on [[a]] the second digital map of the ~~portable~~  
20     navigation apparatus receiver based on the string of  
21     coordinates line information and the additional  
22     information.

1           **Claim 2 (previously presented):** A location  
2       information transmission method according to claim 1,  
3       wherein a string of coordinates where coordinate data  
4       indicating the positions of the nodes and interpolation  
5       points included in said road section are arranged  
6       sequentially is used as said string of coordinate  
7       information.

1           **Claim 3 (previously presented):** A location  
2       information transmission method according to claim 2,  
3       wherein an interpolation point that contributes less to  
4       shape matching is omitted from the interpolation points  
5       included in said road section.

1           **Claim 4 (previously presented):** A location  
2       information transmission method according to claim 3,  
3       wherein said interpolation point is omitted from said  
4       interpolation points where a change in bearing is less  
5       than a predetermined angle with respect to bearing from  
6       an adjacent interpolation point or node and a distance  
7       from said interpolation point or node is less than a  
8       predetermined distance.

1           **Claim 5 (previously presented):** A location  
2       information transmission method according to claim 2,  
3       wherein said string of coordinate information comprises  
4       coordinate data of a member chosen from a group of nodes

5 and interpolation points included in said road section,  
6 the coordinate data being represented using absolute  
7 coordinates and data of members of nodes and  
8 interpolation points excluding said chosen member, the  
9 data being represented using relative coordinates.

1       **Claim 6 (previously presented):** A location  
2 information transmission method according to claim 1,  
3 wherein said additional information includes at least one  
4 information item chosen from a group consisting of road  
5 type code, road number, toll highway code, number of  
6 traffic lanes, regulation information, road width, number  
7 of connecting links to a crossing node, and connection  
8 angle of each connecting link to a crossing node.

1       **Claim 7 (previously presented):** A location  
2 information transmission method according to claim 6,  
3 wherein said additional information includes accuracy  
4 information relating to a digital map data used to  
5 generate the on-road location information.

1       **Claim 8 (previously presented):** Method for  
2 thinning-out a plurality of points representing a road  
3 shape by an information transmission system, comprising  
4 steps of:  
5           providing a string of coordinates defining said  
6 plurality of points;

7           determining whether the bearing deviation,  $d_n$ , of an  
8       interpolation point,  $P_n$ , of said string of coordinates  
9       from a preceding interpolation point,  $P_{n-1}$ , of said string  
10      of coordinates is smaller than a predetermined angle,  $\alpha$ ;  
11           determining whether a distance,  $g_n$ , of the  
12       interpolation point,  $P_n$ , from the preceding interpolation  
13       point,  $P_{n-1}$ , is shorter than a predetermined length,  $\beta$ ;  
14       and  
15           omitting the interpolation point,  $P_n$ , from the string  
16       of coordinates if both  $d_n < \alpha$  and  $g_n < \beta$  as determined in the  
17       determining steps;  
18           transmitting the string of coordinates from which  
19       the interpolation point,  $P_n$ , is omitted from the  
20       information transmission system.

1           **Claim 9 (previously presented):** The method of claim  
2       8, further comprising a step of incrementing the value of  
3       n by 1 and then repeating the steps of determining and  
4       the step of omitting.

1           **Claim 10 (previously presented):** The method of  
2       claim 8 wherein each of the points is represented using  
3       relative information based on one of the plurality of  
4       points.

1           **Claim 11 (currently amended):** A location  
2       information transmission method according to claim 1,  
3       wherein the on-road location information includes  
4       relative information indicating an on-road location in  
5       said road section, the method further comprising a step  
6       of performing identifying the on-road location in the  
7       road section using the relative information by the  
8       receiver portable navigation apparatus.

1           **Claim 12 (new):** A transmission apparatus  
2       comprising:  
3           a digital map;  
4           an information generator that generates, based on  
5       the digital map, on-road location information including:  
6       a string of coordinates line information representing a  
7       road shape of a road section and additional information  
8       including an information item selected from a group  
9       consisting of attribute information on said road section  
10      including a road location of said road section and  
11      detailed information on nodes in said road section; and  
12      a transmitter that transmits the on-road location  
13      information to a receiving apparatus having a digital map  
14      different from the digital map of the transmission  
15      apparatus.

16           **Claim 13 (new):** A receiving apparatus comprising:  
17       a digital map;

18           a receiver that receives on-road location  
19       information including: a string of coordinates line  
20       information representing a road shape of a road section  
21       and additional information including an information item  
22       selected from a group consisting of attribute information  
23       on said road section including a road location of said  
24       road section and detailed information on nodes in said  
25       road section from a transmission apparatus having a  
26       digital map different from the digital map of the  
27       receiving apparatus;  
28           an identifying unit that performs shape matching to  
29       identify said road section on the digital map fo the  
30       receiving apparatus based on the on-road location  
31       information.